

## Chap 5.

5.1

●

$$\rho c \frac{\partial T}{\partial t} = k \frac{d^2 T}{dx^2} + g$$

0 (steady state)

B.C.'s

$$x=0 \quad T = T_1$$

$$x=L \quad T = T_2$$

$$\frac{dT}{dx} = -\frac{g}{k}x + C_1$$

$$T = -\frac{g}{k} \frac{x^2}{2} + C_1 x + C_2$$

$$T = \frac{gL^2}{2k} \left[ \frac{x}{L} - \left( \frac{x}{L} \right)^2 \right] + (T_2 - T_1) \frac{x}{L} + T_1$$

(a)

$$g=0$$

Chap. 4

$$T = (T_2 - T_1) \frac{x}{L} + T_1$$

가 .

(b)  $T_1 = T_2 = T_w$

$$T = \frac{gL^2}{2k} \left[ \frac{x}{L} - \left( \frac{x}{L} \right)^2 \right] + T_w$$

$$x=L/2$$

B.C.'s

$$x=0 \quad T = T_w \quad x=L \quad T = T_w$$

$$x=L/2 \quad \frac{dT}{dx} = 0$$

$$5.1(c) \quad x \quad -L/2$$

B.C.'s

$$x=-L/2 \quad T = T_w \quad x=L/2 \quad T = T_w$$

$$x=0 \quad \frac{dT}{dx} = 0$$

●

5-1(c)

가

$$q = -k \left. \frac{dT}{dx} \right|_{x=L/2} = \frac{gL}{2}$$

$$(Q = gAL) \quad gAL/2 \text{ 가}$$

●

가

5.2

$x=0$

$x=L$

가

$$\frac{d^2T}{dx^2} + \frac{g}{k} = 0$$

$$x=0 \quad \frac{dT}{dx} = 0$$

$$x=L \quad -k \frac{dT}{dx} = h_\infty (T - T_\infty)$$

$$T = \frac{gL^2}{2k} \left[ 1 - \left( \frac{x}{L} \right)^2 \right] + \frac{gL}{h_\infty} + T_\infty$$

$$h_\infty \rightarrow \infty \quad x=L \quad T_L \quad T_\infty \text{ 가}$$

$$x=L \quad T = T_\infty$$

$$T = \frac{gL^2}{2k} \left[ 1 - \left( \frac{x}{L} \right)^2 \right] + T_\infty$$

$$h_\infty \rightarrow 0 \quad x=L \quad T = \infty$$

$$\text{가} \quad (t = \infty) \quad T = \infty \text{ 가}$$

( 5-1)

●

$$\frac{1}{r} \frac{d}{dr} \left( r \frac{dT}{dr} \right) + \frac{g}{k} = 0$$

$$r=0 \quad \frac{dT}{dr} = 0$$

$$r=b \quad T = T_w$$

$$r=0 \quad T \rightarrow \text{finite}$$

$$\frac{d}{dr} \left( r \frac{dT}{dr} \right) = -\frac{g}{k} r$$

$$r \frac{dT}{dr} = -\frac{g}{k} \frac{r^2}{2} + C_1$$

$$\frac{dT}{dr} = -\frac{g}{k} \frac{r}{2} + \frac{C_1}{r} : \quad \frac{dT}{dr} = 0 \quad , C_1 = 0.$$

$$T = -\frac{g}{k} \frac{r^2}{4} + C_1 \ln r + C_2 : \quad T \rightarrow \text{finite} \quad C_1 = 0.$$

$$T = -\frac{g}{k} \frac{r^2}{4} + C_2$$

$$r=b \quad T = T_w$$

$$T = \frac{g}{k} \frac{b^2}{4} \left[ 1 - \left( \frac{r}{b} \right)^2 \right] + T_w$$

$$q = -k \frac{dT}{dr} = \frac{qr}{2}$$

$$Q(r) = q(r)A(r) = \frac{qr}{2} \times 2\pi r L = g\pi r^2 L : r=r$$

$$T_{CL} = \frac{g}{k} \frac{b^2}{4} + T_w$$

● 가

$$\frac{1}{r} \frac{d}{dr} \left( r \frac{dT}{dr} \right) + \frac{g}{k} = 0$$

$$r=0 \quad \frac{dT}{dr} = 0 \quad T \rightarrow \text{finite}$$

$$r=b \quad -k \frac{dT}{dr} = h_{\infty} (T - T_{\infty})$$

$$T = \frac{gb^2}{4k} \left[ 1 - \left( \frac{r}{b} \right)^2 \right] + \frac{gb}{h_\infty} + T_\infty$$

$$h_\infty \rightarrow \infty, \quad h_\infty = 0$$

$$( \quad 5-2)$$

$$( \quad 5-3)$$

$$g = g_0 \left[ 1 - \left( \frac{r}{b} \right)^2 \right]$$

$$\frac{1}{r} \frac{d}{dr} \left( r \frac{dT}{dr} \right) + \frac{g_0}{k} \left[ 1 - \left( \frac{r}{b} \right)^2 \right] = 0$$

$$r=0 \quad \frac{dT}{dr} = 0$$

$$r=b \quad T = T_w$$

$$( \quad 5-4)$$

$$\frac{1}{r} \frac{d}{dr} \left( r \frac{dT}{dr} \right) + \frac{g}{k} = 0$$

$$r=a \quad T = 0$$

$$r=b \quad T = 0$$

● 가

$$\frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{dT}{dr} \right) + \frac{g}{k} = 0$$

$$r=0 \quad \frac{dT}{dr} = 0 \quad T \rightarrow \text{finite}$$

$$r=b \quad -k \frac{dT}{dr} = h_{\infty} (T - T_{\infty})$$

$$\frac{d}{dr} \left( r^2 \frac{dT}{dr} \right) = -\frac{g}{k} r^2$$

$$r^2 \frac{dT}{dr} = -\frac{g}{k} \frac{r^3}{3} + C_1$$

$$\frac{dT}{dr} = -\frac{g}{k} \frac{r}{3} + \frac{C_1}{r^2} : \quad \frac{dT}{dr} = 0 \quad , C_1 = 0.$$

$$T = -\frac{g}{k} \frac{r^2}{6} - \frac{C_1}{r} + C_2 : \quad T \rightarrow \text{finite} \quad C_1 = 0.$$

$$T = -\frac{g}{k} \frac{r^2}{6} + C_2$$

$$r=b$$

$$T = \frac{g}{k} \frac{b^2}{6} \left[ 1 - \left( \frac{r}{b} \right)^2 \right] + \frac{gb}{3h_{\infty}} + T_{\infty}$$

$$h_{\infty} \rightarrow \infty, h_{\infty} = 0$$

$$T_{CL} = \frac{g}{k} \frac{b^2}{6} + \frac{gb}{3h_{\infty}} + T_{\infty}$$

( 5-5)