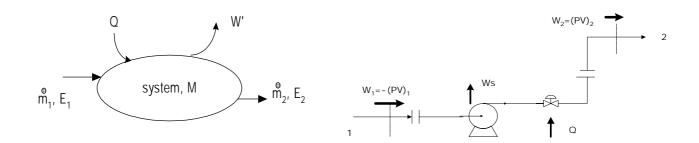
# Chapter 1

# MATERIAL TRANSPORT

## 1.1 Fundamental Relationships

### 1.1.1 Energy Balances



Let the *system* of concern for balance equations be a lumped parameter system surrounded by a fixed boundary. The energy balance around the system is represented by

$$\dot{m}_1\bar{E}_1 - \dot{m}_2\bar{E}_2 + Q - W' = \frac{d}{dt}\left(\bar{E}M\right)$$

where  $\dot{m}$  is the mass flow rate;  $\bar{E}$  represents the energy content per unit mass of the fluid: Q and W' represent heat flow from the surrounding and work delivered on the surrounding by the system per unit time.

If only the internal energy, kinetic energy, and potential energy (by gravity) are concerned

for the energy of the fluid,

$$\bar{E} = \bar{U} + \frac{v^2}{2\alpha g_c} + \frac{g}{g_c}z$$

where v = q/S = mixing cup average velocity,  $\alpha = \begin{cases} 1 & \text{for turbulent flow} \\ 0.5 & \text{for laminar flow} \end{cases}$ 

Rate of work done on the surrounding W' are composed of two terms, shaft work  $(W_s)$  plus PV work of the system on the surrounding at the inlet and outlet of the flow.

$$W' = W_s + \dot{m}_2 (P\bar{V})_2 - \dot{m}_1 (P\bar{V})_1 = W_s + \dot{m}_2 \left(\frac{P}{\rho}\right)_2 - \dot{m}_1 \left(\frac{P}{\rho}\right)_1$$

where  $\bar{V}$  denotes the specific volume of the fluid and  $P_1$  and  $P_2$  are opposing forces against the system at the respective points.

Q: Physical meaning of the PV work?

Summarizing the above with the use of the definition  $\bar{H} = \bar{U} + P\bar{V}$  gives

$$\frac{d}{dt}\left(\bar{U}M\right) = \dot{m}_1 \left(\bar{H} + \frac{g}{g_c}z + \frac{v^2}{2\alpha g_c}\right)_1 - \dot{m}_2 \left(\bar{H} + \frac{g}{g_c}z + \frac{v^2}{2\alpha g_c}\right)_2 + Q - W_s$$

Rate of change of the KE and PE of the system are neglected by assumption (fixed and no motion).

• For closed systems,  $\dot{m} = 0$  and M = constant. Hence

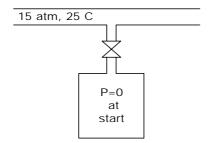
$$Q - \underline{W}_s = \frac{d}{dt}\overline{U}$$
 where  $Q \triangleq Q/M$  and  $\underline{W}_s = W_s/M$ .

• For open systems at steady state ( $\dot{m} = \dot{m}_1 = \dot{m}_2$ ),

$$\bar{H}_1 + \frac{g}{g_c}z_1 + \frac{v_1^2}{2\alpha_1g_c} + \bar{Q} - \bar{W}_s = \bar{H}_2 + \frac{g}{g_c}z_2 + \frac{v_2^2}{2\alpha_2g_c}$$

where  $\bar{Q} \triangleq Q/\dot{m}$  and  $\bar{W}_s = W_s/\dot{m}$ .

Q: A well-known example from thermodynamics



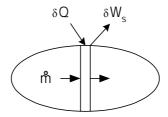
Q: Energy balance around a throttling device and a converging-diverging nozzle



The required (ideal) pumping energy (per unit mass flow of the fluid) is

$$-\bar{W}_s = \frac{g}{g_c}(z_2 - z_1) + \frac{1}{2g_c} \left(\frac{v_2^2}{\alpha_2} - \frac{v_2^1}{\alpha_1}\right) + (\bar{H}_2 - \bar{H}_1) - \bar{Q}$$

- useful for design and analysis of gas transportation systems.
- Conversion of the open-system steady state balance to the **mechanical energy form**



Entropy balance around the differential volume

$$\dot{m}d\bar{S} = \frac{\delta LW(\text{lost work})}{T} + \frac{\delta Q}{T} \implies \delta Q = \dot{m}Td\bar{S} - \delta LW$$

Energy balance around the differential volume

$$\dot{m}d\left(\bar{H} + \frac{g}{g_c}z + \frac{v^2}{2\alpha g_c}\right) = \delta Q - \delta W_s \implies \dot{m}d\left(\bar{H} + \frac{g}{g_c}z + \frac{v^2}{2\alpha g_c}\right) = \dot{m}Td\bar{S} - \delta LW - \delta W_s$$

 $\bar{S}$  is cancelled using  $d\bar{H} = Td\bar{S} + \bar{V}dP$ , we have

$$\bar{V}dP + \frac{g}{g_c}dz + d\frac{v^2}{2\alpha g_c} = -\delta L\bar{W} - \delta \bar{W}_s$$
 where  $\delta L\bar{W} = \delta LW/\dot{m}$   $\delta \bar{W}_s = \delta W_s/\dot{m}$ 

Integrating over the volume yields

$$\frac{g}{g_c}z_1 + \frac{v_1^2}{2\alpha g_c} - \bar{W}_s = \frac{g}{g_c}z_2 + \frac{v_2^2}{2\alpha g_c} + \sum_{\int \delta LW} F_i + \int_1^2 \frac{1}{\rho(P)} dP \quad [\text{energy/mass}]$$

where  $F_i$  is the mechanical energy loss due to friction.

For incompressible fluids,

$$\frac{g}{g_c}z_1 + \frac{v_1^2}{2\alpha g_c} + \frac{p_1}{\rho} - \bar{W}_s = \frac{g}{g_c}z_2 + \frac{v_2^2}{2\alpha g_c} + \sum F_i + \frac{p_2}{\rho}$$

The required pumping energy is

$$-\bar{W}_s = \frac{g}{g_c}(z_2 - z_1) + \frac{v_2^2 - v_1^2}{2\alpha g_c} + \frac{p_2 - p_1}{\rho} + \sum_i F_i$$

- used for piping design for liquid transportation

#### 1.1.2 Friction Factor

• Fanning equation:

$$F = f \frac{2v^2L}{g_cD}$$

- Friction factor f?
  - Pipes and tubes: Refer to Fig. 14-1 in pp. 482.
    - \* Drawn tube tubes drawn through die casting, usually has small diameter (<0.5").
    - \* Commercial steel, wrought iron ordinary process pipes
    - \* Asphalted cast iron external is coated with asphalt. used for piping in sea water or other corrosive environment.

\* galvanized iron - zinc coating, used for utility and underground piping

In practice, 10% to 15% of allowance is given to the required pump horse power to account for roughness that will be developed by corrosion.

 Valves and fittings: Normally use special formulas or the concept of equivalent length.

$$F = f \frac{2v^2 L_e}{g_c D}$$

Refer to Table 1 in pp 484-485.

## 1.2 Piping Practice

## 1.2.1 Piping Standards

### **♦** Pipe

- Used for process and utility piping.
- Size(OD) is referred by the nominal dimension. For example, 1" pipe has 1.32" OD. Refer to Table 13 in pp. 888.
- Pipe strength ( $\propto$  thickness/diameter) is referred by the schedule number.
  - Schedule number =  $1000P_s/S_s = 2000t_m/D_m$  where

 $P_s$  = safe working pressure (psi),  $S_s$  = tensile strength (psi)

 $t_m = \text{mean thickness}, D_m = \text{mean diameter}$ 

Schedule 40 and 80 are usually referred as "standard" and "extra-strong".

#### $\diamondsuit$ Tube

- $\bullet$  Used for s, heat exchangers, instrument air,  $\cdots$
- Nominal size is the true OD. Refer to Table 12 in pp. 886.
- Thickness is defined by BWG (Birmingham Wire Gauge) number.

## $\Diamond$ Fittings

- Fittings union, cross, tee, elbow, 45° elbow
- Thereaded fittings used for small pipes
- Flanges used for 3" or larger pipes
- Screwed fittings used for smaller pipes or tubes
- Bell-and-spigot joint for underground piping

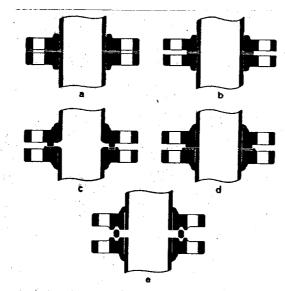


Fig. 3-3. Methods of facing flanges: (a) plain face; (b) raised face; (c) tongue-and-groove face; (d) male and female face; (e) ring joint.

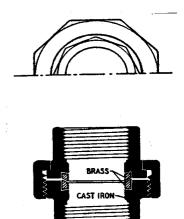


Fig. 3-2. Union.

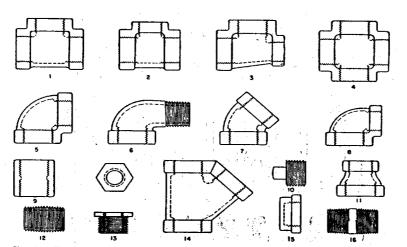


Fig. 3-7. Screwed pipe fittings: (1) tee; (2) tee reducing on outlet; (3) tee reducing on run; (4) cross; (5) elbow; (6) street elbow; (7) 45° clbow; (8) reducing elbow; (9) coupling; (10) plug; (11) reducer; (12) close nipple; (13) bushing; (14) Y branch; (15) cap; (16) short nipple.

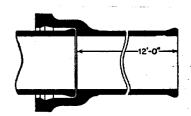
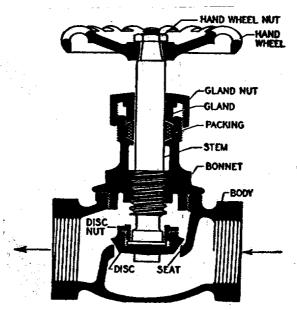


Fig. 3-1. Bell-and-spigot joint for castiron pipe.



Frg. 3-10, Globe valve.

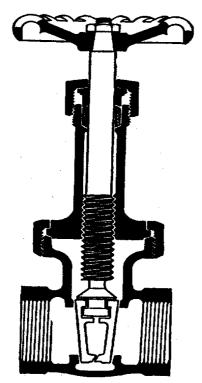


Fig. 3-12. Rising-stem gate valve.

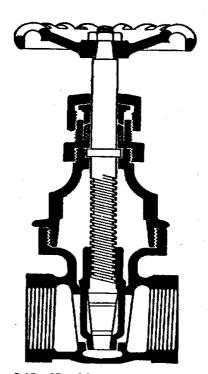
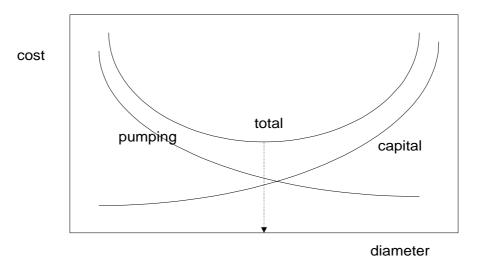


Fig. 3-13. Nonrising-stem gate valve.

## 1.2.2 Pipe Sizing

• need to be optimized between the pumping cost by friction loss and the capital cost.



• Usual Guide

Type of fluid	Reasonable velocity (ft/s)
Normal fluid	3-10
Lo-pressure steam $(25 psig)$	50-100
Hi-pressure steam(100 psig or up)	100-200
Air at ordinary pressure(25-50 psig)	50-100

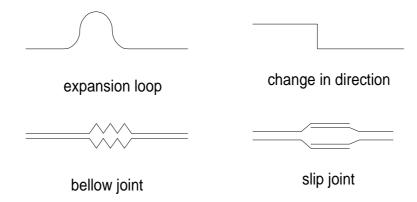
• For estimation of optimum pipe diameter, see Fig. 14-2.

## 1.2.3 Considerations in Piping Design

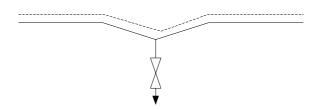
- Effects of temperature level and temperature change
  - Insulation
  - thermal expansion

$$\Delta L = 5''$$
 in  $100ft$  steel pipe for  $\Delta T = 300C$ 

$$\Delta L = 7''$$
 in  $100ft$  steel brass for  $\Delta T = 300C$ 

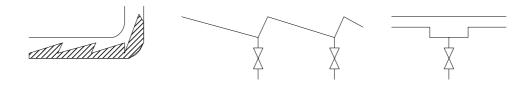


- Freezing, solidification - insulation, steam tracing, sloping to drain valve

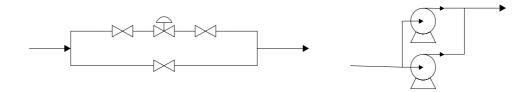


• Flexibility for physical and thermal shock

Drain condensate for prevention of water hammering



- adequate support and anchor
- Alterations in the system and the service
- Maintenance and inspection
- Ease of installation
- Auxiliary or stand-by pumps and lines



ullet Safety - design allowance, relief valves, rupture disks, flare systems  $\cdots$ 

## 1.2.4 Costs for Piping and Piping-System Auxiliaries

Refer to Fig. 14-3 through Fig. 14-34.

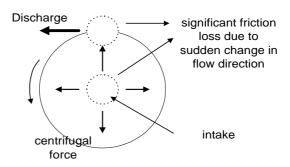
## 1.3 Pumps, Liquid Transportation

- ♦ Factors that Influence Pump Selection
  - Flow rate
  - Pressure (head)
  - Fluid properties: density, viscosity, slurry, corrosion, solvent, · · ·
  - Type of flow distribution: pulsating, nonpulsating
  - Type of power supply: electric, steam, air, hydraulic
  - Cost and mechanical efficiency

## 1.3.1 Rotary Centrifugal Pumps

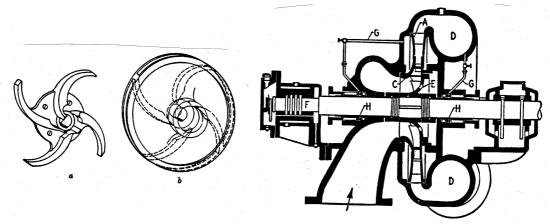
- Fluid transportation by centrifugal force
- Cannot be used gases or vapor
- Most widely used for liquid transportation

## $\Diamond$ Principle



## $\Diamond$ Impeller type

- (a) open-impeller volute pump
- (b) closed-impeller volute pump
- (c) turbine pump



### $\Diamond$ Performance Relationships for Ideal Centrifugal Pumps

$$\frac{Q_1}{Q_2} = \frac{N_1}{N_2}, \quad \frac{\text{Head}_1}{\text{Head}_2} = \frac{N_1^2}{N_2^2}, \quad \frac{\text{Power}_1}{\text{Power}_2} = \frac{Q_1 \text{Head}_1}{Q_2 \text{Head}_2} = \frac{N_1^3}{N_2^3}$$

## ♦ Pump Efficiency

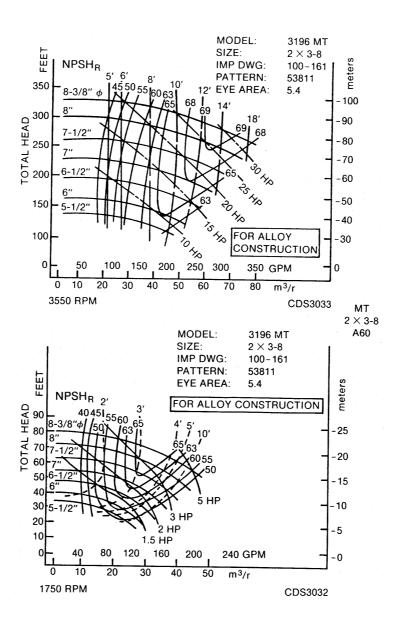
$$\eta_P = \frac{\text{Hydraulic energy delivered to the fluid}(Q\text{Head})}{\text{Break horse power}}$$

where Break horse power = hp delivered to the pump shaft Hence,

Required Motor hp = 
$$\frac{W \text{ from the energy balance}}{\eta_P \eta_M}$$

where  $\eta_M$  is the motor efficiency (  $\approx 80 - 90\%$ ).

### ♦ Performance Curve for Centrifugal Pumps



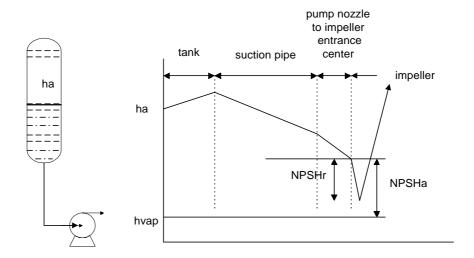
#### **♦** Cavitation

Once cavitation (forming of vapor bubbles) occurs, centrifugal force suddenly drops and pump and/or piping damage is caused.

NPSHr (Net Positive Suction Head Required) = the amount of pump suction head, provided by the pump manufacturer

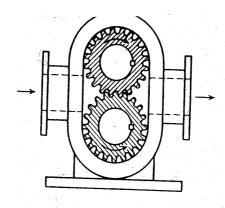
NPSHa (Net Positive Suction Head Available) = estimated pressure at the pump suction entrance point minus vapor pressure of the liquid at the operating conditions.

For no cavitation, NPSHa > NPSHr.



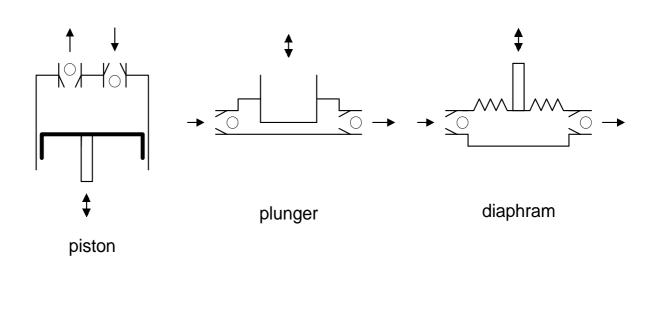
## 1.3.2 Other Types of Pumps

- ♦ Rotary Positive-Displacement Pumps
  - Used for high viscous fluids
  - Gear pump, · · ·

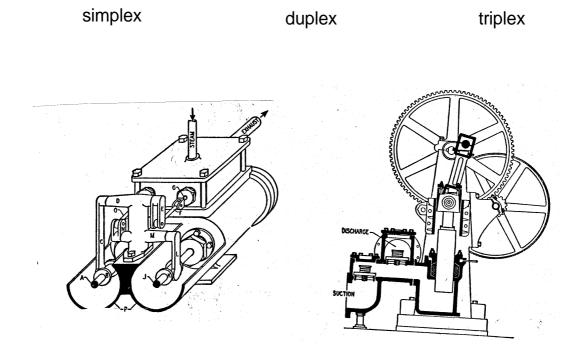


## $\diamondsuit$ Reciprocating or Positive Displacement Pumps with Valve Action

Used when high pumping head is required.





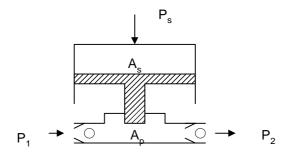


### **♦** Efficiency

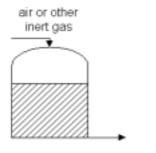
For pumping,

$$A_s P_s \ge A_p P_2 \rightarrow P_2^{max} = \frac{A_s}{A_p} P_s$$

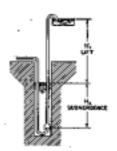
- Volume efficiency = (delivered volume)/(Volume by  $A_p$  strock)
- Pressure efficiency = ( delivered  $P_2$ )/(theoretical  $P_2^{max}$ )



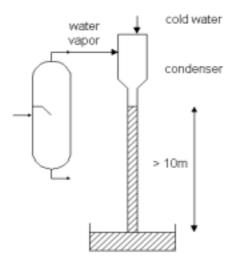
#### ♦ Non-Mechanical Pumping Systems



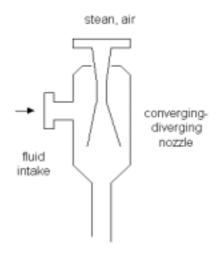
Blow Case or Aicd Egg



Air Lift



Barometric Leg



Ejector or Jet Pump

### 1.3.3 Valve Sizing and Pump Selection

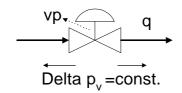
#### Flow Characteristics

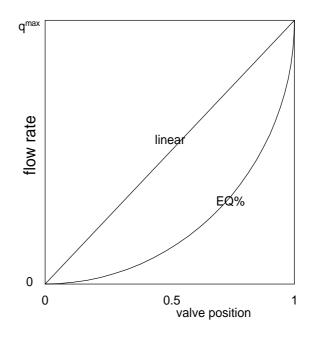
• Ideal valve performance equation

$$q(\mathrm{gal/min}) = C_v \times f(vp) \times \sqrt{\frac{\Delta P_v(\mathrm{psig})}{\mathrm{sp.gr}}}, \quad f(vp) = \left\{ \begin{array}{l} vp \Rightarrow \mathrm{linear} \\ \sqrt{vp} \Rightarrow \mathrm{quick\ opening} \\ R^{vp-1} \Rightarrow \mathrm{equal\ percentage} \end{array} \right.$$

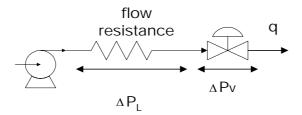
- $C_v$  valve coefficient, customarily refers to the water flow rate (gallon/min) when  $\Delta P_v = 1psig$ . For example,  $C_v = 0.3$  means 0.3[gallon/min] of water can flow when the valve is fully open under  $\Delta P_v = 1psig$ .
- -vp valve position, 0-1.
- -R -rangeability, refers to the ratio of the maximum flow rate (vp=1) to the minimum controllable flow rate (vp=0).
- Intrinsic flow characteristic

When  $\Delta P_v$  is kept constant,





#### • Installed flow characteristic



Assume that  $\Delta P_L + \Delta P_v = \Delta P_o = \text{constant}$ .

Let sp.gr = 1 (water). From

$$\Delta P_L = \frac{sp.gr}{C_L^2} q^2 \qquad \Delta P_v = \frac{sp.gr}{(C_v f(vp))^2} q^2$$

$$\Delta P_O = sp.gr \left[ \frac{1}{C_L^2} + \frac{1}{(C_v f(vp))^2} \right] q^2 = \frac{sp.gr}{C_E(vp)^2} q^2$$

Therefore,

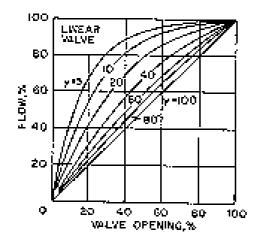
$$q = C_E(vp)\sqrt{\frac{\Delta P_O}{sp.gr}}$$
 where  $\frac{1}{C_E(vp)} = \sqrt{\frac{1}{C_L^2} + \frac{1}{(C_v f(vp))^2}}$ 

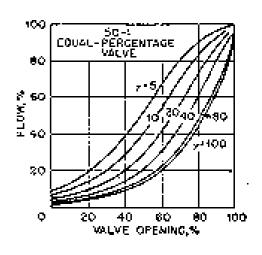
Also

$$\Delta P_v = \frac{C_E^2(vp)}{C_v^2 f(vp)^2} \Delta P_O \quad \Rightarrow \quad \frac{\Delta P_v}{\Delta P_O} = \frac{C_E^2(vp)}{C_v^2 f(vp)^2}$$

Define

$$\gamma = \frac{\Delta P_{v,min}}{\Delta P_{v,max}} = \frac{\Delta P_v(vp=1)}{\Delta P_O} = \frac{1}{1 + (C_v/C_L)^2}$$

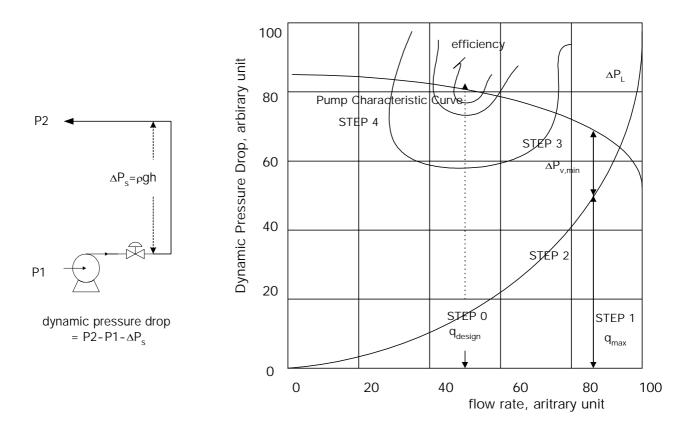




- Since  $\Delta P_v$  decreases as q increases, the flow characteristic of EQ-valve tends to be linearized while that of the linear valve gets nonlinear.
- The nominal opening of a properly sized valve is around 50-70%. Based on this fact,  $\gamma = 5 30\%$  is considered an appropriate choice for the sizing of an EQ% valve in view of linearity.
- An adverse effect for choosing a small  $\gamma$  (large  $C_v$ ) is that the effective rangeabiliy  $(q_{max}/q_{min})$  is decreased. For example,  $R_{effective}=16$  when R=50 and  $\gamma=10\%$ . Hence,  $\gamma=10\sim30\%$ . This can be calculated using

$$\frac{q_{max}}{q_{min}} = \frac{C_E(vp=1)}{C_E(vp=0)} = \frac{\sqrt{1/C_L^2 + R^2/C_v^2}}{\sqrt{1/C_L^2 + 1/C_v^2}} = \frac{\sqrt{C_v^2/C_L^2 + R^2}}{\sqrt{C_v^2/C_L^2 + 1}} = \sqrt{(R^2 - 1)\gamma + 1}$$

## Summary: EQ% Valve Sizing and Pump Selection



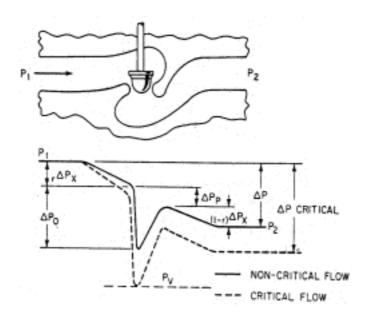
- Step 0: Given a pipeline, or equivalently  $C_L$ , and a design flow rate  $q_{design}$ .
- Step 1: Choose  $q_{max} = (1.5 \sim 2.0) q_{design}$

- Step 2: Draw  $\Delta P_L$  vs. q using  $\Delta P_L = (sp.gr/C_L^2)q^2$ .
- Step 3: Choose  $\Delta P_{v,min}$  as  $10 \sim 30\%$  of  $\Delta P_{L,max}$  at  $q_{max}$ .
- Step 4: Select a pump which has sufficiently high efficiency at  $q_{design}$  and, at the same time, can provide  $\Delta P_{v,min} + \Delta P_{L,max} + \Delta P_s$  of head at  $q_{max}$ .
- Step 5 : Calculate  $C_v$  using

$$C_v = q_{max} \sqrt{\frac{sp.gr}{\Delta P_{v,min}}}$$

#### Further on Valve Performance

#### ♦ Critical Flow Factor



- The dynamic pressure of the fluid becomes minimum at the vena contracta.
- When the minimum pressure is higher than the vapor pressure at the fluid temperature, the fluid is said to be in a *non-critical flow* state.
- Otherwise, we call the flow state as *critical flow*. In the critical flow, part of liquid starts to vaporize. As the fluid pressure is recovered as the fluid flows down along the pipeline, the vapor is condensed to liquid. During this transition, implosion may occurs. This causes noisy sound and vibration.
- Critical flow factor  $C_f$  represents the ratio of  $C_v$  at the critical flow state to  $C_v$  at the normal state.  $C_f$  value is different for different valve design and but usually lies between 0.6 and 0.9.

$$C_f = \frac{C_v \text{ at the critical flow state}}{C_v \text{ at the normal state}}$$

#### **♦ Sizing Equation for Incompressible Fluids**

 $\bullet \,$  For subcritical flow,  $\Delta P < C_f^2 \Delta P_s$ 

$$C_v = q\sqrt{\frac{sp.gr}{\Delta P}}$$

• For critical flow,  $\Delta P \ge C_f^2 \Delta P_s$ 

$$C_v = \frac{q}{C_f} \sqrt{\frac{sp.gr}{\Delta P}}$$

where

$$\Delta P_s[psig] = P_1 - P_{vapor}, \quad \Delta P[psig] = P_1 - P_2$$
  
 $q[gal/min] = \text{volumetric flow rate}$ 

#### ♦ Sizing Equations for Compressible Fluids

For both critical and subcritical states,

• Gases

$$C_v = \frac{Q\sqrt{GT}}{834C_f P_1(y - 0.148y^3)}$$

• Saturated Steam

$$C_v = \frac{W}{1.83C_f P_1(y - 0.148y^3)}$$

• Superheated Steam

$$C_v = \frac{W(1 + 0.0007T_{sh})}{1.83C_f P_1(y - 0.148y^3)}$$

where

$$y = \min \left[ \frac{1.63}{C_f} \sqrt{\frac{\Delta P}{P_1}}, \quad 1.5 \right]$$

 $G = \text{specific gravity of the fluid relative to air at } 1atm, 15^{\circ}C$ 

 $Q = \text{Volumetric flow at } 1atm, 15^{\circ}C(ft^3/min)$ 

 $T_{sh} = \text{degree of superheat}[^{o}F]$ 

W = mass flow rate [lb/min]

## 1.4 Compressors, Gas Transporation

## 1.4.1 Gas Transportation Devices

- Fan  $\Delta P < 0.5 psi$
- Blower  $\Delta P < 50psi$
- Compressor  $\Delta P$  up 4,000 atm or more
- Vacuum pump

### 1.4.2 Compressors

#### **Performance Equation**

$$\frac{g}{g_c}z_1 + \frac{v_1^2}{2\alpha g_c} + H_1 + Q + W = \frac{g}{g_c}z_2 + \frac{v_2^2}{2\alpha g_c} + H_2$$

Usually  $\Delta v^2$ ,  $\Delta z$  and Q are much smaller than  $\Delta h$  and W. Hence

$$H_2(T_2, P_2) - H_1(T_1, P_1) = W$$

- 1. The above relationship (adiabatic compression) holds for both reciprocating compressors as well as rotary compressors.
- 2. The reverse process to the compressor is the expander (usually turbines).
- 3. Note that all the thermodynamic properties in the above and in the subsequent derivations are on the unit-molar basis.

#### Two Ideal Compressors: Isentropic and Isothermal Compressors for an Ideal Gas

- Isentropic Compressor :  $S_2 = S_1$  reversible process (no lost work)
  - PVT Relationship:

For any single component gas, S = S(T, P) also S = S(T, V).

For the first relationship and the ideal gas law,

$$dS = \left(\frac{\partial S}{\partial T}\right)_P dT + \left(\frac{\partial S}{\partial P}\right)_T dP = \frac{C_p}{T} dT - \left(\frac{\partial V}{\partial T}\right)_P dP = C_p d \ln T - Rd \ln P$$

For the second relationship and the ideal gas law,

$$dS = \left(\frac{\partial S}{\partial T}\right)_{V} dT + \left(\frac{\partial S}{\partial V}\right)_{T} dV = \frac{C_{v}}{T} dT + \left(\frac{\partial P}{\partial T}\right)_{V} dV = C_{v} d \ln T + R d \ln V$$

dS = 0 implies

$$\ln \frac{T_2}{T_1} = \frac{R}{C_p} \ln \frac{P_2}{P_1}$$
 and  $\ln \frac{T_2}{T_1} = -\frac{R}{C_v} \ln \frac{V_2}{V_1}$ 

Hence, we obtain

$$\frac{T_2}{T_1} = \left(\frac{V_2}{V_1}\right)^{-R/C_v}, \quad \frac{T_2}{T_1} = \left(\frac{P_2}{P_1}\right)^{R/C_p} \quad \text{and} \quad \frac{P_2}{P_1} = \left(\frac{V_2}{V_1}\right)^{-C_p/C_v} \tag{1.1}$$

– Enthalpy Change and Required Work:

From

$$dH = TdS + VdP$$

and dS expression in the above,

$$dH = C_p dT + \left[ V - T \left( \frac{\partial V}{\partial T} \right)_P \right] dP$$

Inserting the ideal gas law yields

$$dH = C_p dT \quad \to \quad W = \Delta H = C_p (T_2 - T_1) \tag{1.2}$$

Using (1.1) and (1.2), we can obtain

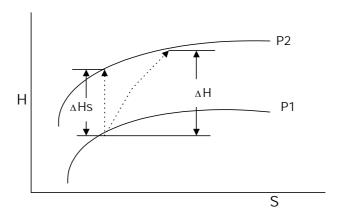
$$W_S = \frac{k}{k-1} P_1 V_1 \left[ \left( \frac{P_2}{P_1} \right)^{(k-1)/k} - 1 \right] \quad \text{(energy/mole)} \quad \text{where} \quad k = C_p / C_v$$

• Isothermal Compressor :  $T_2 = T_1$ 

$$W_T = P_1 V_1 \ln \left( \frac{P_2}{P_1} \right)$$

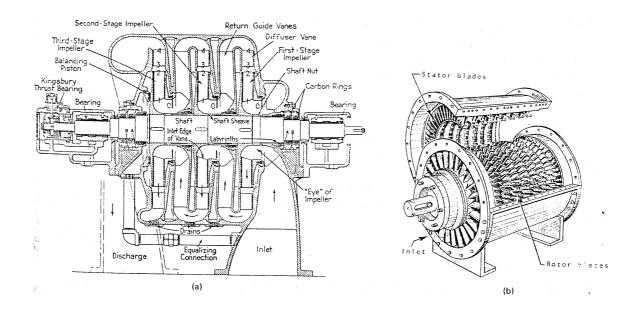
### **Efficiency**

$$\eta = \frac{\text{Theoretical Power Required}}{\text{Actual Power Required}} = \frac{\Delta H_S}{\Delta H_{true}} = \frac{(P_2/P_1)^{(k-1)/k} - 1}{(T_2/T_1) - 1}$$



#### Types and Characteristics of Rotary Compressors

• Centrifugal compressor vs. axial compressor



#### • Surge Problem

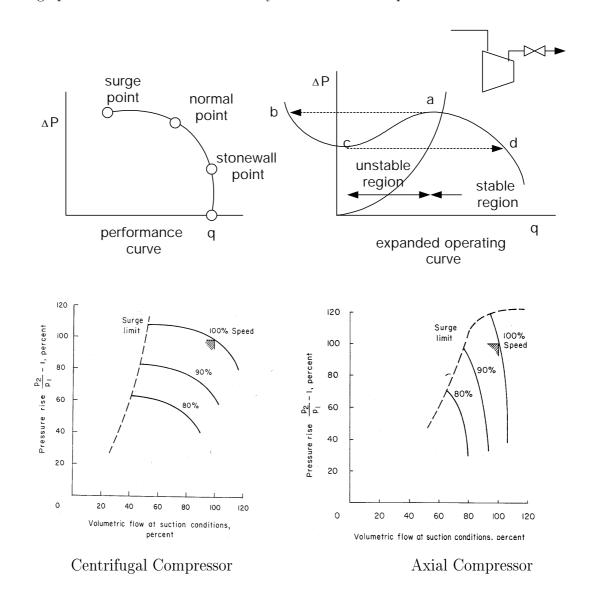
After the stonewall point, opening the valve wider does not increase the flow rate more as the velocity approaches the sonic velocity somewhere in the compressor.

Closing the valve causes the discharge pressure to rise and the throughput to decrease. As the valve is closed further, an aero-dynamical instability, called "surge", occurs.

Surge refers to a very fast repetition (with period of less than 1 or 2 seconds) between sudden back-flow and high forward flow of gas. When the load curve meets the compressor performance curve at "a", the system oscillates along a-b-c-d-a. It is due to the negative resistance (unstable) characteristic of rotary compressors.

Surge causes serious damage to the compressor.

Surge protection control is mandatory in industrial compressors



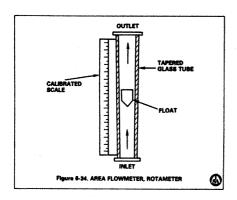
## 1.4.3 Costs for Pumping Machinery

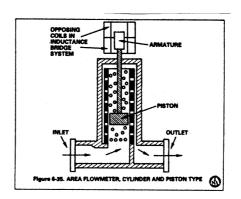
Fig.14-39 through 14-54

# 1.5 Flow Measuring Equipments

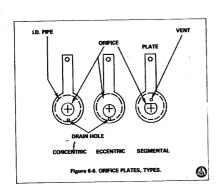
INSTALLATION FACTORS	Pressure Loss	Available from ¼ in. to 30 in. of water — constant throughout meter range.	Available from 1 to 200 in. of water —constant thoughout meter range	Available from 1 to 800 in. of water — varies as square of flow change	Up to 7 psi (varies with flow)	Up to 7 psi (varies with flow)	None	None
	Installation Limits	Meter body must be installed in vertical plane	Meter body must be installed in vertical plane	Horizontal or Vertical	Horizontal Recom- mended	Operates in any position	Horizontal or Vertical	Horizontal or Vertical
	Power Requirements for Basic Measurement	None	None	None	None	Power Supply Needed (115 v, 60 c, 350 w)	Power Supply Needed (115 v, 60 c, 100 w)	Power Supply Needed (115 v, 60 c, 200 w)
	Special Piping Considerations	None	None	Straight pipe run required for approx. 10 pipe diameters upstream, 3 downstream	Мопе	None	Straight pipe run required for approx. 10 pipe diam. upstream	None
	Normal Connections	Screwed or Flanged	Flanged	Screwed or Flanged	Screwed or Flanged	Screwed or Flanged	Flanged	Flanged
	Line Sizes Available	¼ in. to 4 in.	½ in. to 12 in.	2 in. and up	½ in. to 12 in.	½ in. to 6 in.	2 in, and up	1 in. to 12 in.
APPLICATION FACTORS	Construction Materials Available	All Metals Plastics Ceramics (floats and fittings)	All Metals	Steel and Stainless Steel (purges or seal pots used on corrosive services)	Bronze Steel Stainless Steel	Most Metals	Bronze Steel Stainless Steel	Kel-F or Neoprene lined — Stainless Steel
	Type of Scale	Linear	Linear	Square Root	Linear	Linear	Linear	Linear
	Accuracy	±2% of full scale uncali- brated; ±1% of full scale calibrated	±2% of full scale uncali- brated; ±1% of full scale calibrated	11% of dif- ferential measured— additive to accuracy of primary restriction	0.1% - 0.5% of total volume	±0.5% of rate	±2% of full scale	±1% of full scale
	Individual Meter Range	10:1	10:1	4:1 useful range	Up to 20:1	Up to 15:1	20:1	20:1
	Range of I Maximum Flows	% cc/min to 200 gpm	0.1 to 5000 gpm	100 gpm. and up	1 to 5000 gpm	0.25 to 2500 gpm	200 gpm and higher	5 to 5000 gpm
LIMITATIONS	Suitability for Slurries,	Not Recom- mended	Recom- mended	Requires purges of pressure top connections	Not Recom- mended	Not Recom- mended	Recom- mended	Recom- mended
	Temperature Limits	-50°F to +400°F	-300°F to +1600°F	-60°F to +400°F	0°F to +300°F	-300°F to +700°F	-300°F to +600°F	-200°F to +360°F
FLUID PROPERTY	Pressure Limits	Varies with sizes 44 in 300 psi 11. in 200 psi 11. in. 100 psi 2 in and larger - 50 psi larger - 50 psi	150 lb ASA to 2500 lb ASA	To 1500 psi	150 lb ASA to 300 lb ASA standard	Up to 3000 psi	Up to 1500 psi	Up to 600 psi
	Type of Fluid	g Bğ	Suitable for all fluids	Suitable for most fluids	Suitable for all clean or filtered fluids	Suitable for all clean or filtered liquids	Suitable for most liquids	Suitable for most liquids that are electrical conductors
	METER	VARIABLE: AREA Float Type (glass tube)	VARIABLE- AREA Float Type (metal tube)	VARIABLE HEAD (static manometer)	INTEGRATING OR VOLUME (positive displacement	INTEGRATING OR VOLUME (turbine type)	OBSTRUC- TIONLESS (ultrasonic	OBSTRUC- TIONLESS (magnetic type)

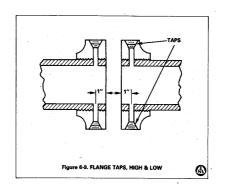
#### $\Diamond$ Area Flow meter

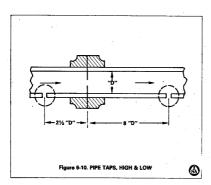


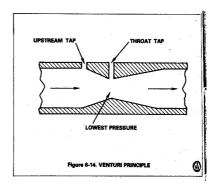


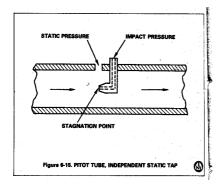
## $\Diamond$ Head Flowmeter

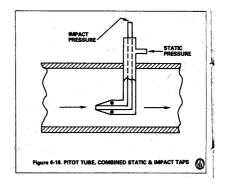




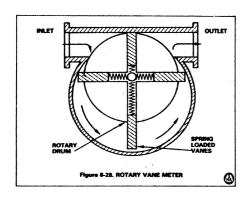


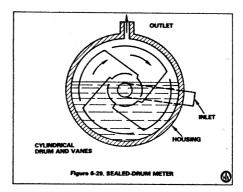


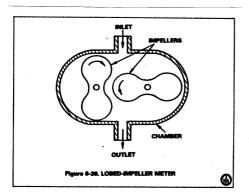


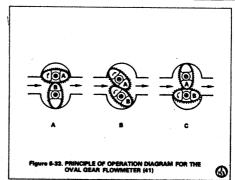


## $\diamondsuit$ Positive Displacement Meter

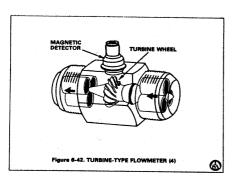


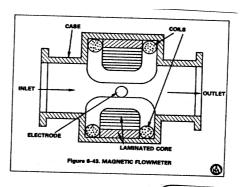


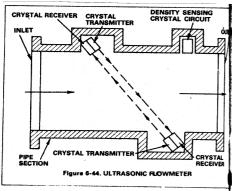


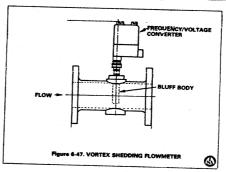


## $\Diamond$ Volumetric Flowmeter

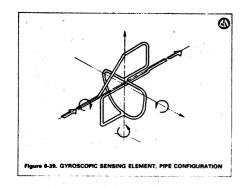


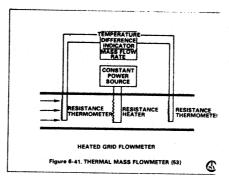






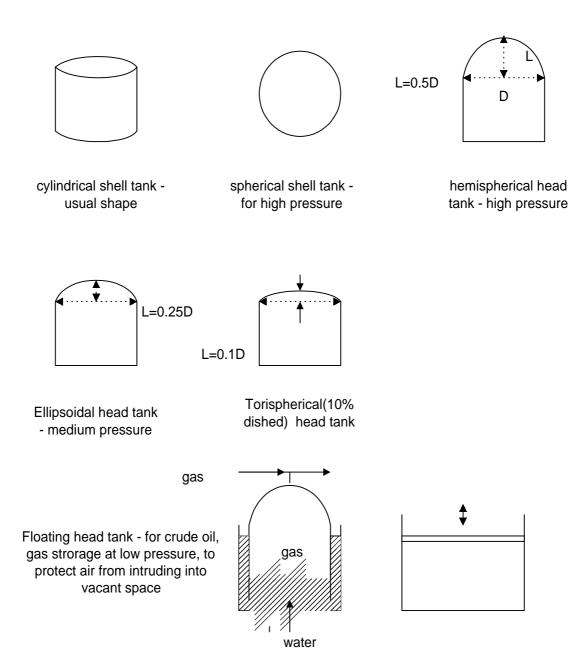
## $\Diamond$ Mass Flowmeter





Plus the mass flow meter using Corilolis force principle.

## 1.6 Tanks and Pressure Vessels



♦ Thickness calculation for cylindrical shell

$$t(\text{inch}) = \frac{P(\text{max.press, pis})r_i(\text{inner radius, in})}{S(\text{tensile strength, psi})E_J(\text{joint/welding efficiency, } 0 - 1) - 0.6P(\text{psi})} + C_c(\text{allowance})$$