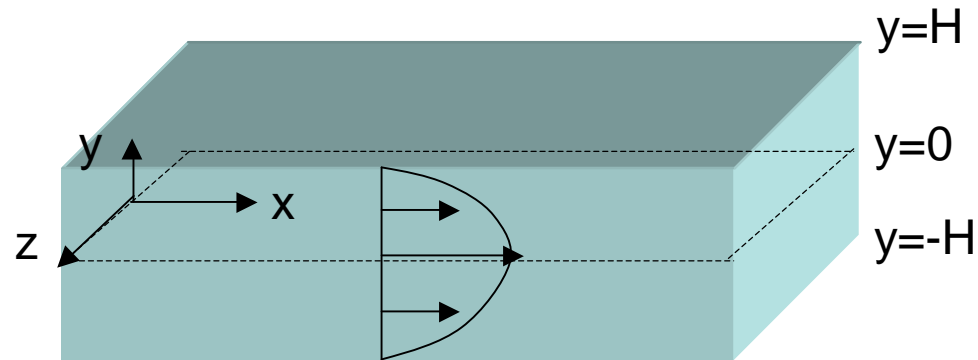


Part III. Linear Stability Analysis of Plane Poiseuille Flow



Equation of Motion:
$$\rho \frac{\partial \underline{\tilde{v}}}{\partial \underline{\tilde{t}}} + \rho \underline{\tilde{v}} \cdot \underline{\tilde{\nabla}} \underline{\tilde{v}} = -\underline{\tilde{\nabla}} \underline{\tilde{P}} + \mu \underline{\tilde{\nabla}}^2 \underline{\tilde{v}} + \rho \underline{\tilde{f}}$$

Dimensionless variables:
$$\underline{v} = \frac{\underline{\tilde{v}}}{u}, \underline{\nabla} = H \underline{\tilde{\nabla}}, P = \frac{\underline{\tilde{P}}}{\rho u^2}, t = \frac{\underline{\tilde{t}}}{H/u}, f = \frac{\underline{\tilde{f}} H}{u^2}$$

(u: maximum velocity, H: half width)

Dimensionless equation of motion:
$$\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \underline{\nabla} \underline{v} = -\underline{\nabla} P + \frac{1}{\text{Re}} \underline{\nabla}^2 \underline{v} + \underline{f}$$

$$(\text{Re} = H u \rho / \mu)$$

(gravity term neglected)

$$\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} = -\frac{\partial P}{\partial x} + \frac{1}{\text{Re}} \left(\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right)$$

$$\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} = -\frac{\partial P}{\partial y} + \frac{1}{\text{Re}} \left(\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right)$$

$$\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} = -\frac{\partial P}{\partial z} + \frac{1}{\text{Re}} \left(\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right)$$

Dimensionless Continuity Equation: $\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} = 0$

Boundary Conditions: $v_x = v_y = v_z = 0$ at $y = \pm 1$

v_x, v_y, v_z bounded at $x, z \rightarrow \pm\infty$

Consider two-dimensional system with width effect neglected ...

By squire's theorem, 2-D disturbance is the most unstable...

Steady-State: $v_{x,s} = v_{x,s}(y) = 1 - y^2$, $v_{y,s} = 0$

$$P_s = P_0 + \left(\frac{\partial P}{\partial x} \right)_x$$

Linearized equations: $v_x(x, y, t) = v_{x,s}(y) + \hat{v}_x(y) \exp(i\alpha(x - ct))$

$$v_y(x, y, t) = 0 + \hat{v}_y(y) \exp(i\alpha(x - ct))$$

$$P(x, y, t) = P_s + \hat{P}(y) \exp(i\alpha(x - ct))$$

Use streamline function to linearize the system:

(two variables v_x , v_y can be unified into one variable, ψ)

$$\psi(x, y, t) = \psi_s(y) + \hat{\psi}(y) \exp(i\alpha(x - ct))$$

$$\Rightarrow v_x = -\frac{\partial \psi}{\partial y} = -\frac{\partial \psi_s}{\partial y} - \frac{\partial \hat{\psi}}{\partial y} \exp(i\alpha(x - ct)) = v_{x,s} - \hat{\psi}' \exp(i\alpha(x - ct))$$

$$\Rightarrow v_y = \frac{\partial \psi}{\partial x} = 0 + i\alpha \hat{\psi} \exp(i\alpha(x - ct))$$

Linearized equation of motion (x-direction) :

$$\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} = -\frac{\partial P}{\partial x} + \frac{1}{\text{Re}} \left(\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} \right)$$

$$\Rightarrow i\alpha c \hat{\psi}' - i\alpha v_{x,s} \hat{\psi}' + i\alpha v'_{x,s} \hat{\psi} = i\alpha \hat{P} + \frac{1}{\text{Re}} \alpha^2 \hat{\psi}' - \frac{1}{\text{Re}} \hat{\psi}''$$

Linearized equation of motion (y-direction) :

$$\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} = -\frac{\partial P}{\partial y} + \frac{1}{\text{Re}} \left(\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} \right)$$

$$\Rightarrow \alpha^2 c \hat{\psi} - \alpha^2 v_{x,s} \hat{\psi} = -\hat{P} - \frac{1}{\text{Re}} i\alpha^3 \hat{\psi} + \frac{1}{\text{Re}} i\alpha \hat{\psi}''$$

Orr-Sommerfeld Eqn.

→ Unified equation: (elimination of pressure disturbance):

$$i\alpha c \hat{\psi}'' - i\alpha^3 c \hat{\psi} = \left(-i\alpha^3 v_{x,s} - \frac{1}{\text{Re}} \alpha^4 - i\alpha v''_{x,s} \right) \hat{\psi}$$

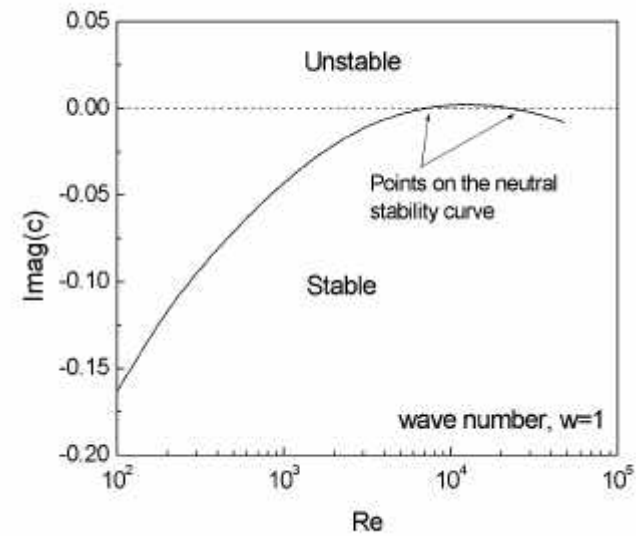
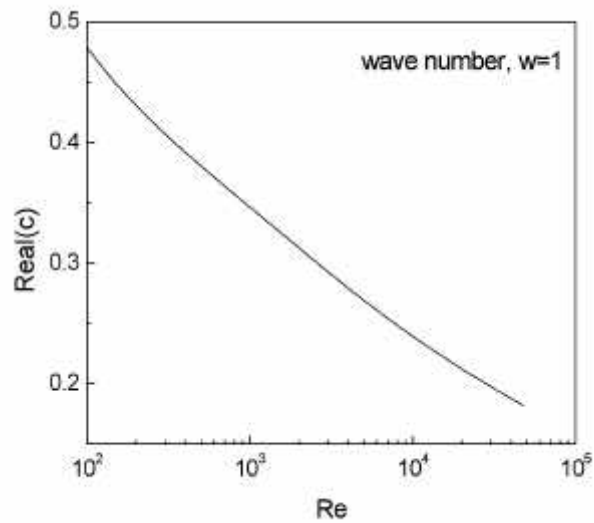
$$+ \left(\frac{2}{\text{Re}} \alpha^2 + i\alpha v_{x,s} \right) \hat{\psi}'' + \left(-\frac{1}{\text{Re}} \right) \hat{\psi}^{iv}$$

Boundary conditions:

$$\hat{\psi}(0) = \hat{\psi}(1) = 0$$

$$\hat{\psi}'(0) = \hat{\psi}'(1) = 0$$

Real and imaginary parts of the first eigenvalue of the Orr-Sommerfeld equation for $w=1$



Neutral stability curve

